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A Multiscale Approach to the Design and Analysis of WEAV3D Lattice Structures

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# Introduction to WEAV3D Lattice Structures







## **WEAV3D Lattice Structures**

Thermoplastic Prepreg Tape Woven into Lattice Structures Embedded in Thermoplastic Structural Components to Provide Cost/Weight/Strength Efficient Reinforcement

Lattice Structure (Thermoplastic Prepreg Tape)



Lattice Structure Embedded in a Precast Polymer Concrete Trench

Lattice Structure Embedded in a Thermoplastic Pallet





Lattice Structure Embedded in a Nature Fiber Nonwoven Mat





# **Rebar for Plastics** <sup>®</sup>



# **Design and Analysis Challenges**

How do you design and analyze something like this? (Example: Automotive Beltline Stiffener)





# **Design and Analysis Challenges**

- What Warp Tape Material (Carbon, Glass, other)?
- What Fill Tape Material (Carbon, Glass, other)?
- What Tape Width (Warp & Fill)?
- What Tape Gap (Warp & Fill)?
- How Many Lattice Layers (Top & Bottom)
- What Bulk Material?

Even if we know these things, how to analyze structures made from these lattice structures?





# **Design and Analysis Challenges**

## **Discrete Modeling**

VS

-Explicitly model features -typically most Accurate Results -can be Difficult to Model -can be Computationally Expensive

## **Multiscale Modeling**

Implicitly model features
-can achieve Accurate Results
-significantly Easier Modeling
-can be Computationally Efficient



# Introduction to a Proposed Multiscale Solution

## **BE BOUNDLESS**

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## **Proposed Multiscale Solution**

"All truths are easy to understand once they are discovered; the point is to discover them." Galileo Galilei

We are simply connecting already discovered puzzle pieces to assemble a new puzzle picture



# Puzzle Piece #1 Classical Lamination Theory

One of the earlier forms of Multiscale Analysis...



homogenization (upscaling)



starting from the strain of the  $k^{th}$  ply  $(\varepsilon)_k = (\varepsilon^0) + z_k(\kappa)$  $(\sigma)_{k} = [\bar{Q}]_{k} ((\varepsilon)_{k} - (\alpha)_{k} \Delta T)$  $(\sigma)_k dz$ (N) = $\int [\bar{Q}]_k \left( (\varepsilon^o) + z_k(\kappa) - (\alpha)_k \Delta T \right) dz$  $(N) = \sum_{n=1}^{\infty}$  $(N) = [A](\varepsilon^o) + [B](\kappa) - (N_t)$ the homogenized stiffnesses of a laminated plate are;

$$[A] = \sum_{k=1}^{n} [\bar{Q}]_{k} (z_{k} - z_{k-1})$$

$$[B] = \frac{1}{2} \sum_{k=1}^{n} [\bar{Q}]_{k} (z_{k}^{2} - z_{k-1}^{2})$$

$$(N_{t}) = \Delta T \sum_{k=1}^{n} [\bar{Q}]_{k} (\alpha)_{k} (z_{k} - z_{k-1})$$

# Puzzle Piece #1 Classical Lamination Theory

One of the earlier forms of Multiscale Analysis...



# Puzzle Piece #2 Phase Average Theory

Hill, R., "The Mathematical Theory of Plasticity", Oxford University Press, 1950 Hashin, Z., "Theory of Fiber Reinforced Materials", NASA CR-1974, March 1972 The average stress ( $\overline{\sigma}$ ) of all phases (p) is the homogenized stress ( $\sigma^{\circ}$ ) Fundamental result for multiscale applications





# Phase Average Modified Classical Lamination Theory



# Phase Average Modified Classical Lamination Theory

$$[A] = \sum_{k=1}^{n} [\bar{Q}]_k (z_k - z_{k-1})$$
$$[B] = \frac{1}{2} \sum_{k=1}^{n} [\bar{Q}]_k (z_k^2 - z_{k-1}^2)$$
$$[D] = \frac{1}{3} \sum_{k=1}^{n} [\bar{Q}]_k (z_k^3 - z_{k-1}^3)$$

$$(N_t) = \Delta T \sum_{k=1}^{n} [\bar{Q}]_k (\alpha)_k (z_k - z_{k-1})$$
$$(M_t) = \Delta T \frac{1}{2} \sum_{k=1}^{n} [\bar{Q}]_k (\alpha)_k (z_k - z_{k-1})$$

 $\sum_{k=1}^{k}$ 

Phase Modified  

$$[A] = \sum_{k=1}^{n} \left( \sum_{p=1}^{N} [\bar{Q}]_{k}^{p} V_{k}^{p} \right) (z_{k} - z_{k-1})$$

$$[B] = \frac{1}{2} \sum_{k=1}^{n} \left( \sum_{p=1}^{N} [\bar{Q}]_{k}^{p} V_{k}^{p} \right) (z_{k}^{2} - z_{k-1}^{2})$$

$$[D] = \frac{1}{3} \sum_{k=1}^{n} \left( \sum_{p=1}^{N} [\bar{Q}]_{k}^{p} V_{k}^{p} \right) (z_{k}^{3} - z_{k-1}^{3})$$

$$(N_{t}) = \Delta T \sum_{k=1}^{n} \left( \sum_{p=1}^{N} [\bar{Q}]_{k}^{p} (\alpha)_{k}^{p} V_{k}^{p} \right) (z_{k} - z_{k-1})$$

$$(M_{t}) = \Delta T \frac{1}{2} \sum_{k=1}^{n} \left( \sum_{p=1}^{N} [\bar{Q}]_{k}^{p} (\alpha)_{k}^{p} V_{k}^{p} \right) (z_{k} - z_{k-1})$$



 $\binom{N}{M} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \binom{\varepsilon^o}{\kappa} - \binom{N_t}{M_t}$ 



# FEA Implementation & Numerical Validation







# **FEA Implementation & Architecture**

## Currently implemented in Altair HyperWorks (HyperMesh, OptiStruct, HyperView)



# JPanel Input - Lattice + Panel Definitions

## Individual Tape Material Properties (Warp1, Warp2, Fill1, Fill2, Bulk)

(1)	(2) / (6)	(3) / (7)	(4) / (8)	(5) / (9)	(10)
MAT9OR*	MID	E1	E2	E3	MNAME
	NU12	NU23	NU31	RHO	
	G12	G23	G13	A1	
	A2	A3			

#### WEAV3D Lattice Definitions

(1)	(2) / (6)	(3) / (7)	(4) / (8)	(5) / (9)	(10)
LATTICE*	LID	LNAME	GAP_W	GAP_F	
	MID_W1	THK_W1	NUM_W1	WTH_W1	
	MID_W2	THK_W2	NUM_W2	WTH_W2	
	MID_F1	THK_F1	NUM_F1	WHT_F1	
	MID_F2	THK_F2	NUM_F2	WHT_F2	
	MID_LB				



#### Panel Definitions

L	(1)	(2) / (6)	(3) / (7)	(4) / (8)	(5)/(9)	(10)
	<b>PPANEL*</b>	PID	PNAME	TYPE		
		LID	NUM_L	SYM	BOT	
Γ		THK	Z0	NSM	PHI	
		MID_BC	MID_BS	VOL_BS		



# JPanel OUTPUT – MAT2 + PSHELL

Captures the Membrane, Bending, Transverse Shear, and Coupling Behavior

(1)	(2) / (6)	(	(3) / (7)	(4	) / (8)		(5)/(9)	(10)	Multiscale Model
MAT2*	MID		Q11 Q12		Q13				
	Q22		Q23	Q33		RHO			
	A1		A2		A12				
Membrane			Bending						
								~	$\times$
(1)	(2)/(6)		(3) / (7)	(4	4) / (8)		(5) / (9)	(10)	
(1) PSHELL*	(2) / (6) PID	-	<b>3</b> ) / (7) MID1	(4	<b>4) / (8)</b> THK	-	<b>(5) / (9)</b> MID2	(10)	
(1) PSHELL*	(2) / (6) PID 12I/T3	4	3) / (7) MID1 MID3	(4	<b>4)</b> / <b>(8)</b> THK TS/T	-	(5) / (9) MID2 NSM	(10)	
(1) PSHELL*	(2) / (6) PID 12I/T3 Z1	4	3) / (7) MID1 MID3 Z2	(4 	<b>I)</b> / <b>(8)</b> THK TS/T MID4	-	(5) / (9) MID2 NSM	(10)	
(1) PSHELL*	(2) / (6) PID 12I/T3 Z1	1	3) / (7) MID1 MID3 Z2	(4 	4) / (8) THK TS/T MID4	-	(5) / (9) MID2 NSM	(10)	

## **Material Properties**

Glass/PP Uni Tape V<sup>f</sup> = 45%

Property	Gpa	Psi
E <sub>1</sub>	36.00	5.220e6
E <sub>2</sub>	5.000	0.725e6
v <sub>12</sub>	0.300	0.300
V <sub>23</sub>	0.520	0.520
G <sub>12</sub>	1.760	0.255e6
G <sub>23</sub>	1.650	0.240e6
$\alpha_1$	5.4e-6 /ºC	3.0e-6 /°F
α2	36.0e-6 /ºC	20.0e-6 /ºF
СРТ	0.350mm	0.0138"
ρ	1.650 g/cm <sup>3</sup>	0.0596 lbs/in <sup>3</sup>

#### Carbon/PP Uni Tape V<sup>f</sup> = 50%

Property	GPa	psi
E <sub>1</sub>	110.0	15.950e6
E <sub>2</sub>	4.800	0.696e6
v <sub>12</sub>	0.320	0.320
V <sub>23</sub>	0.480	0.480
G <sub>12</sub>	2.000	0.290e6
G <sub>23</sub>	1.620	0.235e6
$\alpha_1$	-0.54e-6 /ºC	-0.30e-6 /°F
α2	40.0e-6 /ºC	22.22e-6 /ºF
СРТ	0.160mm	0.0063"
ρ	1.310 g/cm <sup>3</sup>	0.0473 lbs/in <sup>3</sup>

### Polypropylene (PP) Polymer

Property	GPa	psi
E	1.950	0.2828e6
ν	0.380	0.380
G	0.70652	0.1025e6
α	54.0e-6 /ºC	30.0e-6 /ºF
ρ	0.906 g/cm <sup>3</sup>	0.0327 lbs/in <sup>3</sup>

## Lattice Geometry Extreme Case

#### Warp Geometry

 $V^{w1}$  = 20% (Glass/PP Tape)  $V^{w2}$  = 40% (Carbon/PP Tape)  $V^{wb}$  = 20% (PP Polymer Bulk)

#### **Fill Geometry**

V<sup>f1</sup> = 28.57% (Carbon/PP Tape) V<sup>f2</sup> = 14.29% (Glass/PP Tape) V<sup>fb</sup> = 57.14% (PP Polymer Bulk)

#### **Panel Geometry**

2 lattice layers bottom only Unsymmetric in-plane and through-thickness



## In-plane Load (Nx Case) and a Thermal Processing Load ( $\Delta$ T Case)



## **Bending Load (Mx Case)**

Unsymmetric In-plane and through-thickness

## Exercises Bending and Bending/In-Plane Coupling Behavior of Panels

$$\begin{bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} & A_{14} & B_{11} & B_{12} & B_{14} \\ A_{12} & A_{22} & A_{24} & B_{12} & B_{22} & B_{24} \\ A_{14} & A_{24} & A_{44} & B_{14} & B_{24} & B_{44} \\ B_{11} & B_{12} & B_{14} & D_{11} & D_{12} & D_{14} \\ B_{12} & B_{22} & B_{24} & D_{12} & D_{22} & D_{24} \\ B_{14} & B_{24} & B_{44} & D_{14} & D_{24} & D_{44} \end{bmatrix} \begin{bmatrix} \mathcal{E}_x^o \\ \mathcal{E}_y^o \\ \mathcal{Y}_{xy}^o \\ \mathcal{K}_x \\ \mathcal{K}_y \\ \mathcal{K}_{xy} \end{bmatrix} - \begin{bmatrix} N_{t,x} \\ N_{t,y} \\ \mathcal{K}_{t,xy} \\ \mathcal{M}_{t,y} \\ \mathcal{M}_{t,xy} \end{bmatrix}$$



## **Discrete vs Multiscale Model**

## **Discrete Modeling**

VS

-Explicitly model features -typically most Accurate Results -can be Difficult to Model -can be Computationally Expensive

## Multiscale Modeling

Implicitly model features
-can achieve Accurate Results
-significantly Easier Modeling
-can be Computationally Efficient



# **Numerical Validation - Displacements**

Min = -3.051E+00

## **Nx Case**

Correctly bends "up" and all displacements within ±1% error of approximation



#### **Discrete Model**



#### **Multiscale Model**







Min = -3.050E+00

# **Numerical Validation - Displacements**

## $\Delta x$ Case

Correctly bends "down" and all displacements within ±1% error of approximation



#### **Discrete Model**

### **Multiscale Model**











# **Numerical Validation - Displacements**

**U**<sub>2</sub>

## **Mx Case**

The in-plane unsymmetric geometry (extreme case) is not completely accounted for and causes increased but acceptable in-plane error but out-of-plane error still within ±1% error of approximation



#### **Discrete Model**





### **Multiscale Model**







 $\otimes\,\sigma_x^{\text{ panel bulk}}$ 

 $\otimes\,\sigma_x^{\text{ lattice warp1}}$ 

 $\otimes\,\sigma_x^{\text{ lattice warp2}}$ 

(Carbon/PP)

 $\otimes\,\sigma_x^{\text{ lattice bulk}}$ 

🔽 na

(Glass/PP)

(PP)

## **Nx** Case

The primary axial stress in each phase are captured and within ±10% error of approximation

## **Discrete Model**

Contour Plot

3.000E+01 1.167E+01

-6 667E±00 -2.500E+01 -4.333E+0

-6.167E+01 -8.000E+01

-9.833E+01

-1.167E+02

-1.350E+02 No Result

Max = 2.818E+01

Min = 2.800E+01 Contour Plot

> 3.000E+01 1.167E+01

-6.667E+00

-2.500E+01

-4.333E+01 -6.167E+01

-8.000E+01 -9.833E+01

-1.167E+02 -1.350E+02

Max = -4.044E+01 Min = -4.570E+01

Contour Plot

3.000E+01 1.167E+01

-6.667E+00 -2.500E+01 -4.333E+01

-6.167E+01

-8.000E+01

-9.833E+01

-1.167E+02 -1.350E+02 No Result

Max = -1.294E+02

Min = -1.354E+02 Contour Plot

3.000E+01

1.167E+01

-6.667E+00

-2.500E+01

-4.333E+01

-6.167E+01 -8.000E+01

-9.833E+01

-1.167E+02 1.350E+02 No Result

Max = -1.628E+00

Min = -2.431E+00

## **Multiscale Model**



1.3505+02

Max = -2.030E+00

Min = -2.030E+00

## $\Delta x$ Case

The thermal residual axial stress in each phase are captured and within ±10% error of approximation



Composite Stresses(Normal X Stress, ply7\_Bulk (TOP))

Contour Plot

4.000E+01

#### **Discrete Model**

#### **Multiscale Model**

Contour Plot

Phase Stress(XX, SST) Analysis system

## $\Delta x$ Case

The thermal residual transverse stress in each phase are captured and within ±10% error of approximation



 $\otimes\,\sigma_x^{\text{ panel bulk}}$ 

(PP)

Contour Plot

2.500E+01 1.833E+01

1.167E+01

5.000E+00

-1.667E+00

-8.333E+00

-1.500E+01

-2.167E+01

-2.833E+01

-3.500E+01 No Result

Max = -4.169E+00

Min = -4.325E+00

Composite Stresses(Normal Y Stress, ply7\_Bulk (TOP))

#### **Discrete Model**

### **Multiscale Model**











 $\otimes\,\sigma_x^{\text{ panel bulk}}$ 

(PP)

## **Mx Case**

The primary axial stress in bending in each phase are captured and within ±10% error of approximation



Contour Plot

1.500E+01 -8.889E+00

-3.278E+01 -5.667E+01

-8.056E+01

-1.044E+02

-1.283E+02

-1.522E+02

-1.761E+02 -2.000E+02 No Result

Max = 1.604E+01

Min = -2.039E+02

Composite Stresses(Normal X Stress, ply7\_Bulk (TOP)

## **Discrete Model**

#### **Multiscale Model**







## Conclusions

- Discrete Modeling Methods for the Design and Analysis of WEAV3D Lattice Structures is impractical for general use cases
- Multiscale Methods appear to be a reasonable solution to the challenges of analyzing and designing WEAV3D Lattice Structures
- The error of approximation of such approaches appears to be within acceptable engineering error tolerances of ±10%
- The significant reduction in effort to create and apply the multiscale modeling, as opposed to discrete modeling, and given acceptable error of approximation, warrants the use multiscale modeling for this problem...

# **Continuing Project Phases**





# **Continuing Forward**

- 1. Experimental Test Program for Tape Properties
- 2. Experimental Test Program for 3pt Bend Panels
- 3. Numerical Verification (comparison of simulation with experiment as opposed to discrete model presented here)
- 4. Optimization Methodology & Software
- 5. An Optimization Example with Verification

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